DIRE: A Neural Approach to Decompiled Identifier Renaming

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Software Engineering Institute **Carnegie Mellon**











Reverse Engineering

26 Feb 2013 | 14:00 GMT

The Real Story of Stuxnet

How Kaspersky Lab tracked down the malware that stymied Iran's nuclear-fuel enrichment program



By David Kushner

Computer cables snake across the floor. Cryptic flowcharts are scrawled across various whiteboards adorning the walls. A life-size Batman doll stands in the hall. This office might seem no different than any other geeky workplace, but in fact it's the front line of a war-a cyberwar, where most battles play out not in remote jungles or deserts but in

2014 IEEE International Conference on Software Maintenance and Evolution

Reverse Engineering PL/SQL Legacy Code: An Experience Report

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Abstract—The reengineering of legacy code is a tedious endeavor. Automatic transformation of legacy code from an old technology to a new one preserves potential problems in legacy code with respect to obsolete, changed, and new business cases. On the other hand, manual analysis of legacy code without assistance of original developers is time consuming and errorprone. For the purpose of reengineering PL/SQL legacy code in the steel making domain, we developed tool support for the reverse engineering of PL/SQL code into a more abstract and comprehensive representation. This representation then serves as input for stakeholders to manually analyze legacy code, to identify obsolete and missing business cases, and, finally, to support the re-implementation of a new system. In this paper we briefly introduce the tool and present results of reverse engineering PL/SQL legacy code in the steel making domain. We show how stakeholders are supported in analyzing legacy code by means of general-purpose analysis techniques combined with domain-specific representations and conclude with some of the lessons learned.

Keywords—reverse engineering; program comprehension; source code analysis

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- Changes in business cases over the last years were not reflected in verification logic of the legacy code.
- For a new production plant, additional requirements must be incorporated.
- The maintenance of the legacy programs was complicated by the retirement of original developers.
- Legacy code is not extensible in a safe and reliable way.
- Stakeholders estimated high effort for manual analysis of the legacy code.

The goal for the reverse engineering tool was to support stakeholders to comprehend the verification logic implemented in the legacy programs. Whereas, comprehension requires that stakeholders can (1) *identify* the business cases currently checked by the software as well as that stakeholders are able to (2) *extend* the verification logic with respect to new requirements.

The contributions of this paper are:

Disassembler

	1. jlacom	is@gs17931:~/Data	/coreutils/	debug/src (ssh)
40299c:	89 f0		mov	%esi,%eax
40299e:	83 e0 04	4	and	\$0x4,%eax
4029a1:	74 1d		je	4029c0 <main+0x8b0></main+0x8b0>
4029a3:	31 d2		xor	%edx,%edx
4029a5:	48 89 da	3	mov	%rbx,%rax
4029a8:	48 f7 f	7	div	%rdi
4029ab:	48 89 0	5 be b8 20 00	mov	%rax,0x20b8be(%rip)
4029b2:	48 89 1	5 ff ba 20 00	mov	%rdx,0x20baff(%rip)
4029b9 :	4d 85 c	9	test	%r8,%r8
4029bc:	75 14		jne	4029d2 <main+0x8c2></main+0x8c2>
4029be:	eb 31		jmp	4029f1 <main+0x8e1></main+0x8e1>
4029c0:	48 83 fl	o ff	cmp	\$0xfffffffffffffffffff,%rb
4029c4:	74 07		je	4029cd <main+0x8bd></main+0x8bd>
4029c6:	48 89 10	d a3 b8 20 00	mov	%rbx,0x20b8a3(%rip)
4029cd:	4d 85 c	9	test	%r8,%r8
4029d0:	74 1f		je	4029f1 <main+0x8e1></main+0x8e1>
4029d2:	89 c8		mov	%ecx,%eax
4029d4:	83 e0 10	9	and	\$0x10,%eax
4029d7:	74 18		je	4029f1 <main+0x8e1></main+0x8e1>



Disassembler

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Library function Regular function	📕 Instruction 📄 Data 📕 Unexplored 📒 External syn
📠 Graph overview	[IDA View-A
	xor edx, edx
	div rdi
	mov cs:skip_rec
	mov cs:skip_byte
	cmp rbx, OFFFFF
	jnz short loc_4
	jmp short loc_40
	loc 4029C0:
	cmp rbx
	iz sho
	<u></u>
	100.00% (3865,13067) (657,9) 00002996 00000000
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X IDA - dd /media/DATA/coreutils/debug/src/dd - 12 🗗 🗊 🕈 🎬 🚮 🚽 🖈 📹 🗙 🛛 🕨 🔲 🔲 No debugger 77 External symbol 275 usage(1); 276 } 277 v8 = v7 + 1;switch (___ROR1___(*v6 - 99, 1)) 278 279 { 280 case 0: if (v6[1] != 111) 281 goto LABEL_46; 282 if (v6[2] != 110) 283 284 goto LABEL_46; if (v6[3] != 118) 285 286 goto LABEL_46; v9 = v6[4];287 if (v9) 288 289 { 290 if (v9 != 61) 291 goto LABEL_46; 292 293 conversions_mask |= parse_symbols(v8, conversions, 0, "invalid goto LABEL_90; 294 295 case 3: if (v6[1] != 102) 296 goto LABEL_46; 297 298 v12 = v6[2];if (v12 && v12 != 61) 299 300 { 301 if (v12 == 108 && v6[3] == 97 && v6[4] == 103)302 303 v13 = v6[5];if (!v13 || v13 == 61) 304 305 { 00003F47 main:275 (403F47) • DØX

<u>F</u> ile <u>E</u> dit Jump Sear	275	usage(1);
8 📂 🔒 8 🗢 → → → 📘	276	}
	277	v8 = v7 + 1;
	278	switch (ROR1(*v6 - 99
Library function	279	{
[IDA View-A	280	case 0:
	281	if $(v6[1] != 111)$
• • •	282	goto LABEL_46;
	283	if (v6[2] != 110)
	284	goto LABEL_46;
loc_402AF1 test bl	285	if (v6[3] != 118)
jnz lo	286	goto LABEL_46;
	287	v9 = v6[4];
	288	if (v9)
	289	{
loc_40	290	if (v9 != 61)
test	291	goto LABEL_46;
2	292	}
	293	conversions_mask = pa
	294	goto LABEL_90;
call	295	case 3:
mov	296	if (v6[1] != 102)
db	297	goto LABEL_46;
nop	298	v12 = v6[2];
	299	if (v12 && v12 != 61
	300	{
	301	if (v12 == 108 && v
ut file[rex] call	302	{
100.00% (3396,12163)	303	v13 = v6[5];
Output window	304	if (!v13 v13 =
60E608; using queese	305	{
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The problem:

Decompilers are typically unable to assign meaningful names to variables


```
void *file_mmap(int V1, int V2)
{
  void *V3;
  V3 = mmap(0, V2, 1, 2, V1, 0);
  if (V3 == (void *) -1) {
    perror("mmap");
    exit(1);
  }
  return V3;
```

```
Today
       Refactored decompiler output
       void *file_mmap(int fd, int size)
       {
         void *ret;
         ret = mmap(0, size, 1, 2, fd, 0);
         if (ret == (void *) -1) {
           perror("mmap");
           exit(1);
         }
         return ret;
```


Today

```
void *file_mmap(int(V1)
                         int V2)
{
  void *V3;
  V3 = mmap(0, V2, 1, 2, (V1) 0);
  if (V3 == (void *) -1) {
    perror("mmap");
    exit(1);
  return V3;
```

```
Refactored decompiler output
void *file_mmap(int(fd) int size)
{
  void *ret;
  ret = mmap(0, size, 1, 2, (fd) 0);
  if (ret == (void *) -1) {
    perror("mmap");
    exit(1);
  return ret;
```



```
void *file_mmap(int V1, int(V2)
  void *V3;
  V3 = mmap(0, V2) 1, 2, V1, 0);
  if (V3 == (void *) -1) {
    perror("mmap");
    exit(1);
  return V3;
```

Today Refactored decompiler output void *file_mmap(int fd, int size) { void *ret; ret = mmap(0, size) 1, 2, fd, 0); if (ret == (void *) -1) { perror("mmap"); exit(1);return ret;

Today Refactored decompiler output void *file_mmap(int fd, int size) ret ret = mmap(0, size, 1, 2, fd, 0); (ret)== (void *) -1) { if perror("mmap"); exit(1); ret

Up to ______ recovery of original source code names on an open-source GitHub corpus

up to 74%

Why does it work?

Key principle: Software is "natural" (2012 International Conference on Software Engineering)

On the Naturalness of Software

Abram Hindle, Earl Barr, Zhendong Su Dept. of Computer Science University of California at Davis Davis, CA 95616 USA *{ajhindle,barr,su}@cs.ucdavis.edu*

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efforts in the 1960s. In the '70s and '80s, the field was re-Abstract—Natural languages like English are rich, complex, and powerful. The highly creative and graceful use of languages animated with ideas from logic and formal semantics, which like English and Tamil, by masters like Shakespeare and still proved too cumbersome to perform practical tasks at Avvaiyar, can certainly delight and inspire. But in practice, scale. Both these approaches essentially dealt with NLP from given cognitive constraints and the exigencies of daily life, most first principles—addressing *language*, in all its rich theoretical human utterances are far simpler and much more repetitive glory, rather than examining corpora of actual utterances, i.e., and predictable. In fact, these utterances can be very usefully modeled using modern statistical methods. This fact has led what people actually write or say. In the 1980s, a fundamental to the phenomenal success of statistical approaches to speech shift to corpus-based, statistically rigorous methods occurred. recognition, natural language translation, question-answering, The availability of large, on-line corpora of natural language and text mining and comprehension. text, including "aligned" text with translations in multiple We begin with the conjecture that most software is also

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```
void *file_mmap(int V1, int V2)
{
  void *V3;
  V3 = mmap(0, V2, 1, 2, V1, 0);
  if (V3 == (void *) -1) {
    perror("mmap");
    exit(1);
  }
  return V3;
```

Recal

Refactored decompiler output

```
void *file_mmap(int fd, int size)
{
  void *ret;
```

```
ret = mmap(0, size, 1, 2, fd, 0);
```

```
if (ret == (void *) -1) {
```

```
perror("mmap");
```

```
exit(1);
```

```
}
return ret;
```


Learn typical variable names in a given context from examples ... many many examples

If software is repetitive, so are names int main(int ?

Idea: Learn typical variable names in a given context from examples ... many many examples

If software is repetitive, so are names int main(int banana

Idea: Learn typical variable names in a given context from examples ... many many examples

If software is repetitive, so are names int main(int argc

Good news: We can generate arbitrarily many examples

GitHub () + Compiler/Decompiler 💥 + Time 🚍

Source code with meaningful names

 $\mathcal{L}_{\mathfrak{R}}$

Original Source

• • •	emacs		
1#include <	<stdio.h></stdio.h>		
2			
3int main()	{		
4 int $x =$	0;		
5 int $y =$	0;		
6 while (×	< < 100) {		
7 printf	⁻ ("%d∖n", x);		
8 x++;			
9 }			
10 return y	/;		
11}			
-UUU:**F1	count.c	All	(11, 1)

Corpus Construction

	• •		e	emacs			
	1#:	include <	stdio.h>	>			
	2						
	3iı	nt main()	{				
	4	int v1 =	0;				
	5	int v2 =	0;				
	6	while (v	1 < 100)) {			
	7	printf	("%d\n",	, v1);			
	8	v1++;					
	9	}					
	10	return v	2;				
	11}						
	-UUI	J:**F1	count.c		All	(11,1)	

Original Source

Corpus Construction

 #1	$\mathbf{O} ullet$	emacs			
	1#include <stdio.h< th=""><th>1></th><th></th><th></th><th></th></stdio.h<>	1>			
	2				
	<pre>3int main() {</pre>				
	4 inc $v1 = 0;$				
	5 inc $v^2 = 0;$				
	6 while (v1 < 100)) {			
	7 printf("%d\n"	', ∨1);			
	8 v1++;				
	9 }				
	10 return v2;				
	11}				
	-UUU:**F1 count.	С	All	(11,1)	

Original Source

• •	emacs
1#include <stdio< td=""><td>.h></td></stdio<>	.h>
2	
<pre>3int main() {</pre>	
4 int $x = 0$;	
5 int y = 0;	
6 while (x < 100	ð) {
7 printf("%d\r	יי ר, x);
8 x++;	
9 }	
10 return y;	
11}	
-UUU:**F1 count	t.c All (11,1)

Original Source

Different function signatures

Decompiled Code

Original Source

Different numbers of variables

Original Source

Decompiled Code

Different types of loops

Original Source

• •	emacs
1#include <stdio< td=""><td>.h></td></stdio<>	.h>
2	
<pre>3int main() {</pre>	
4 int $x = 0$;	
5 int y = 0;	
6 while (x < 100	ð) {
7 printf("%d\r	יי ר, x);
8 x++;	
9 }	
10 return y;	
11}	
-UUU:**F1 count	t.c All (11,1)

Two different loops.

Alignment

Two different loops.

Alignment

Same assembly code.

var1 = dword ptr -8var2 = dword ptr -4••• •••• mov [rbp+var2], 0 jmp loc_4a5 loc_49B: mov eax, [rbp+var2] add [rbp+var1], eax add [rbp+var2], 1 loc_4a5: cmp [rbp+var2], 9 jle loc_49b

Key insight: Operations on variables and their offsets are the same

Alignment

Key insight: Operations on variables and their offsets are the same

Alignment

Learning from examples

Recall: Names are repetitive in a given context int main(int argc

char* mystrcopy(char *VAR1, char *VAR2){ char *result; if (VAR1 && VAR2) result = strcopy(VAR1, VAR2); else result = 0LL;

return result;

Code can be a sequence of lexical tokens ...

... or a syntax tree

char * mystrcopy (char * VAR1


```
char* mystrcopy(char *VAR1, char *VAR2){
 char *result;
  if (VAR1 && VAR2)
    result = strcopy(VAR1, VAR2);
 else
    result = 0LL;
  return result;
```


Encoder

Lexical Encoder (LSTM)

Structural Encoder (GGNN)

Decoder

Sequential Decoder with Attention

Encoder

Lexical Encoder (LSTM)

Structural Encoder (GGNN)

Lexical Encoder (LSTM)

Structural Encoder (GGNN)

Structural Encoder (GGNN)

Lexical Encoder (LSTM)

Structural Encoder (GGNN)

Decoder

Sequential Decoder with Attention

Structural Encoder (GGNN)

Decoder

Sequential Decoder with Attention

Encoder Lexical Encoder (LSTM) Structural Encoder (GGNN)

Decoder

Identifier Representations Sequential Decoder with Attention

Encoder

Lexical Encoder (LSTM)

Code Element Representations

Structural Encoder (GGNN)

Identifier Representations

Decoder

Sequential Decoder with Attention

Encoder Lexical Encoder (LSTM)

Structural Encoder (GGNN)

Decoder

Code Element Representations

Identifier Representations Sequential Decoder with Attention

Encoder Lexical Encoder (LSTM)

Structural Encoder (GGNN)

Decoder

Code Element Representations

Identifier Representations Sequential Decoder with Attention

How good are the renamings?

Assumption: Original (human-written) names are good How many can we recover?

Dataset

• 164,632 unique x86-64 binaries 1,259,935 decompiled functions Split by binary into test/training/validation Open dataset, link in paper/on ASE site

Variable Recovery Rate (%)

* Meaningful Variable Names for Decompiled Code: A Machine Translation Approach, A. Jaffe, J. Lacomis, E. J. Schwartz, C. Le Goues, and B. Vasilescu, in ICPC, 2018

Structural Prior Work* 64.6 16.2

Variable Recovery Rate (%)

DIRELexical74.372.9

* Meaningful Variable Names for Decompiled Code: A Machine Translation Approach, A. Jaffe, J. Lacomis, E. J. Schwartz, C. Le Goues, and B. Vasilescu, in ICPC, 2018

Variable Recovery Rate (%)

DIRELexical74.372.9

* Meaningful Variable Names for Decompiled Code: A Machine Translation Approach, A. Jaffe, J. Lacomis, E. J. Schwartz, C. Le Goues, and B. Vasilescu, in ICPC, 2018

Structural

64.6

Prior Work* 16.2


```
file f_{open(char **V1, char *V2, int V3) {
 1
      int fd;
 2
 3
      if (!<u>V3</u>)
 4
         return fopen(*<u>V1</u>, <u>V2</u>);
 5
       if (*<u>V2</u> != 119)
 6
         assert_fail("fopen");
 7
       fd = open(*<u>V1</u>, 577, 384);
      if (fd >= 0)
 8
 9
         return reopen(fd, V2);
10
       else
11
         return 0;
12
```

Example

Developer	Lexical	Structural	DIRE
filename	file	fname	filena
mode	name	oname	mode
is_private	mode	flags	creat
	<section-header><section-header><section-header><section-header><section-header><section-header><section-header></section-header></section-header></section-header></section-header></section-header></section-header></section-header>	<pre>Developer Lexical filename file mode name is_private mode</pre>	DeveloperLexicalStructuralfilenamefilefnamemodenameonameis_privatemodeflags

Today			
Decompiler output	Refactored decompiler output		
<pre>void *file_mmap(int V1, int V2) {</pre>	<pre>void *file_mmap(int fd, int size) {</pre>		
<pre>void *V3; V3 = mmap(0, V2, 1, 2, V1, 0); if (V3 == (void *) -1) {</pre>	<pre>void *ret; ret = mmap(0, size, 1, 2, fd, 0); if (ret == (void *) -1) {</pre>		
<pre>perror("mmap"); exit(1); }</pre>	<pre>perror("mmap"); exit(1); }</pre>		
return V3; }	return ret; }		

DIRE Neural Architecture

Software Engineering Institute **Carnegie Mellon**

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William H. Pres William T. Vett

x, float y[], float o y[], float dydx[], flo s, float htot, int nste (float, float [], float est, float xest, float

=1,kmax,kopt,nvold = -1
old = -1.0,xnew;
x,fact,h,red,scale,work
dy,*err,*yerr,*ysav,*ys
MAXX+1];
[KMAXX+1][KMAXX+1];
[MAXX+1]={0,2,6,10,14,2.
ag=0;
1,KMAXX);
;
else if (k
red=1.
break;
}
else if (k
red=al
break;
Nv != nvold) {
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int n);	
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will always converge, *provided* that the initial guess is good enough. Indeed one can even determine in advance the rate of convergence of most algorithms. It cannot be overemphasized, however, how crucially success depends on

It cannot be overemphasized, non-respecially for multidimensional problems. having a good first guess for the solution, especially for multidimensional problems. This crucial beginning usually depends on analysis rather than numerics. Carefully crafted initial estimates reward you not only with reduced computational effort, but also with understanding and increased self-esteem. Hamming's motto, "the purpose of computing is insight, not numbers," is particularly apt in the area of finding roots. You should repeat this motto aloud whenever your program converges, with ten-digit accuracy, to the wrong root of a problem, or whenever it fails to converge because there is actually *no* root, or because there is a root but your initial estimate was not sufficiently close to it.

was not sufficiently close is all very well, but what do I actually do?" For one-"This talk of insight is all very well, but what do I actually do?" For onedimensional root finding, it is possible to give some straightforward answers: You should try to get some idea of what your function looks like before trying to find its roots. If you need to mass-produce roots for many different functions, then you should at least know what some typical members of the ensemble look like. Next, you should always bracket a root, that is, know that the function changes sign in an identified interval, before trying to converge to the root's value.

Finally (this is advice with which some daring souls might disagree, but we give it nonetheless) never let your iteration method get outside of the best bracketing bounds obtained at any stage. We will see below that some pedagogically important algorithms, such as *secant method* or *Newton-Raphson*, can violate this last constraint, and are thus not recommended unless certain fixups are implemented

Multiple roots, or very close roots, are a real problem, especially if the multiplicity is an even number. In that case, there may be no readily apparent sign change in the function, so the notion of bracketing a root — and maintaining the bracket — becomes difficult. We are hard-liners: we nevertheless insist on bracketing a root, even if it takes the minimum-searching techniques of Chapter 10 to determine whether a tantalizing dip in the function really does cross zero or not. (You can easily modify the simple golden section routine of §10.1 to return early if it detects a sign change in the function. And, if the minimum of the function is exactly zero, then you have found a *double* root.)

As usual, we want to discourage you from using routines as black boxes without understanding them. However, as a guide to beginners, here are some reasonable starting points:

- Brent's algorithm in §9.3 is the method of choice to find a bracketed root of a general one-dimensional function, when you cannot easily compute the function's derivative. Ridders' method (§9.2) is concise, and a close competitor.
- When you can compute the function's derivative, the routine rtsafe in §9.4, which combines the Newton-Raphson method with some bookkeeping on bounds, is recommended. Again, you must first bracket your root.
- Roots of polynomials are a special case. Laguerre's method, in §9.5, is recommended as a starting point. Beware: Some polynomials are ill-conditioned!
- Finally, for multidimensional problems, the only elementary method is Newton-Raphson (§9.6), which works very well if you can supply a

good first guess of the solution. Try it. Then read the more advanced material in §9.7 for some more complicated, but globally more convergent, alternatives.

Avoiding implementations for specific computers, this book must generally steer clear of interactive or graphics-related routines. We make an exception right now. The following routine, which produces a crude function plot with interactively scaled axes, can save you a lot of grief as you enter the world of root finding.

#include <stdio.h> #define ISCR 60 Number of horizontal and vertical positions in display. #define JSCR 21 #define BLANK ', #define ZERO '-, #define YY '1' #define XX '-' #define FF 'x' void scrsho(float (*fx)(float)) For interactive CRT terminal use. Produce a crude graph of the function fx over the promptedfor interval x1, x2. Query for another plot until the user signals satisfaction. int jz, j, i; float ysml,ybig,x2,x1,x,dyj,dx,y[ISCR+1]; char scr[ISCR+1][JSCR+1]; for (;;) { printf("\nEnter x1 x2 (x1=x2 to stop):\n"); Query for another plot, quit scanf("%f %f",&x1,&x2); if x1=x2. if (x1 == x2) break; for (j=1;j<=JSCR;j++)</pre> Fill vertical sides with character '1' scr[1][j]=scr[ISCR][j]=YY; for (i=2;i<=(ISCR-1);i++) {</pre> scr[i][1]=scr[i][JSCR]=XX; Fill top, bottom with character '-'. for (j=2;j<=(JSCR-1);j++) Fill interior with blanks. scr[i][j]=BLANK; dx=(x2-x1)/(ISCR-1);x=x1; ysml=ybig=0.0; Limits will include 0. for (i=1;i<=ISCR;i++) {</pre> Evaluate the function at equal intervals. Find the largest and smallest valy[i] = (*fx)(x);if (y[i] < ysml) ysml=y[i];</pre> if (y[i] > ybig) ybig=y[i]; x += dx;Be sure to separate top and bottom. if (ybig == ysml) ybig=ysml+1.0; dyj=(JSCR-1)/(ybig-ysml); Note which row corresponds to 0. jz=1-(int) (ysml*dyj); Place an indicator at function height and for (i=1;i<=ISCR;i++) {</pre> scr[i][jz]=ZERO; j=1+(int) ((y[i]-ysml)*dyj); scr[i][j]=FF; printf(" %10.3f ",ybig); for (i=1;i<=ISCR;i++) printf("%c",scr[i][JSCR]);</pre> printf("\n"); Display. for (j=(JSCR-1); j>=2; j--) { printf("%12s"," "); for (i=1;i<=ISCR;i++) printf("%c",scr[i][j]);</pre> printf("\n"); printf(" %10.3f ",ysml);

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It cannot be overemphasized, non-respecially for multidimensional problems. having a good first guess for the solution, especially for multidimensional problems. This crucial beginning usually depends on analysis rather than numerics. Carefully crafted initial estimates reward you not only with reduced computational effort, but also with understanding and increased self-esteem. Hamming's motto, "the purpose of computing is insight, not numbers," is particularly apt in the area of finding roots. You should repeat this motto aloud whenever your program converges, with ten-digit accuracy, to the wrong root of a problem, or whenever it fails to converge because there is actually *no* root, or because there is a root but your initial estimate was not sufficiently close to it.

was not sufficiently close is all very well, but what do I actually do?" For one-"This talk of insight is all very well, but what do I actually do?" For onedimensional root finding, it is possible to give some straightforward answers: You should try to get some idea of what your function looks like before trying to find its roots. If you need to mass-produce roots for many different functions, then you should at least know what some typical members of the ensemble look like. Next, you should always bracket a root, that is, know that the function changes sign in an identified interval, before trying to converge to the root's value.

Finally (this is advice with which some daring souls might disagree, but we give it nonetheless) never let your iteration method get outside of the best bracketing bounds obtained at any stage. We will see below that some pedagogically important algorithms, such as *secant method* or *Newton-Raphson*, can violate this last constraint, and are thus not recommended unless certain fixups are implemented

Multiple roots, or very close roots, are a real problem, especially if the multiplicity is an even number. In that case, there may be no readily apparent sign change in the function, so the notion of bracketing a root — and maintaining the bracket — becomes difficult. We are hard-liners: we nevertheless insist on bracketing a root, even if it takes the minimum-searching techniques of Chapter 10 to determine whether a tantalizing dip in the function really does cross zero or not. (You can easily modify the simple golden section routine of §10.1 to return early if it detects a sign change in the function. And, if the minimum of the function is exactly zero, then you have found a *double* root.)

As usual, we want to discourage you from using routines as black boxes without understanding them. However, as a guide to beginners, here are some reasonable starting points:

- Brent's algorithm in §9.3 is the method of choice to find a bracketed root of a general one-dimensional function, when you cannot easily compute the function's derivative. Ridders' method (§9.2) is concise, and a close competitor.
- When you can compute the function's derivative, the routine rtsafe in §9.4, which combines the Newton-Raphson method with some bookkeeping on bounds, is recommended. Again, you must first bracket your root.
- Roots of polynomials are a special case. Laguerre's method, in §9.5, is recommended as a starting point. Beware: Some polynomials are ill-conditioned!
- Finally, for multidimensional problems, the only elementary method is Newton-Raphson (§9.6), which works very well if you can supply a

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#include <stdio.n>
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#define ISCR 60
#define JSCR 21
#define BLANK ', ',
#define ZERO '--'
#define YY '1'
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#define FF 'x'

void scrsho(float (*fx)(float))

For interactive CRT terminal use. Produce a crude graph of the function fx over the promptedfor interval x1, x2. Query for another plot until the user signals satisfaction.

int jz,j,i;
float ysml,ybig,x2,x1,x,dyj,dx,y[ISCR+1];
char scr[ISCR+1][JSCR+1];

for (;;) {

```
printf("\nEnter x1 x2 (x1=x2 to stop):\n");
                                                   Query for another plot, quit
scanf("%f %f",&x1,&x2);
                                                       if x1=x2.
if (x1 == x2) break;
for (j=1;j<=JSCR;j++)</pre>
                                         Fill vertical sides with character '1'
   scr[1][j]=scr[ISCR][j]=YY;
for (i=2;i<=(ISCR-1);i++) {</pre>
    scr[i][1]=scr[i][JSCR]=XX;
                                         Fill top, bottom with character '-'.
    for (j=2;j<=(JSCR-1);j++)
                                         Fill interior with blanks.
        scr[i][j]=BLANK;
dx=(x2-x1)/(ISCR-1);
x=x1;
ysml=ybig=0.0;
                                         Limits will include 0.
for (i=1;i<=ISCR;i++) {</pre>
                                          Evaluate the function at equal intervals.
                                             Find the largest and smallest val-
    y[i] = (*fx)(x);
    if (y[i] < ysml) ysml=y[i];</pre>
    if (y[i] > ybig) ybig=y[i];
    x += dx;
                                          Be sure to separate top and bottom.
if (ybig == ysml) ybig=ysml+1.0;
dyj=(JSCR-1)/(ybig-ysml);
                                          Note which row corresponds to 0.
jz=1-(int) (ysml*dyj);
                                          Place an indicator at function height and
for (i=1;i<=ISCR;i++) {</pre>
    scr[i][jz]=ZERO;
    j=1+(int) ((y[i]-ysml)*dyj);
    scr[i][j]=FF;
printf(" %10.3f ",ybig);
for (i=1;i<=ISCR;i++) printf("%c",scr[i][JSCR]);</pre>
printf("\n");
                                          Display.
for (j=(JSCR-1); j>=2; j--) {
    printf("%12s"," ");
    for (i=1;i<=ISCR;i++) printf("%c",scr[i][j]);</pre>
   printf("\n");
```

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understanding them. However, as a guide to beginners, here are some reasonable starting points:

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For interactive CRT terminal use. Produce a crude graph of the function fx over the promptedfor interval x1,x2. Query for another plot until the user signals satisfaction.

```
x += dx;
                                        Be sure to separate top and bottom.
if (ybig == ysml) ybig=ysml+1.0;
dyj=(JSCR-1)/(ybig-ysml);
                                        Note which row corresponds to 0.
jz=1-(int) (ysml*dyj);
                                        Place an indicator at function height and
for (i=1;i<=ISCR;i++) {</pre>
    scr[i][jz]=ZERO;
   j=1+(int) ((y[i]-ysml)*dyj);
    scr[i][j]=FF;
printf(" %10.3f ",ybig);
for (i=1;i<=ISCR;i++) printf("%c",scr[i][JSCR]);</pre>
printf("\n");
for (j=(JSCR-1); j>=2; j--) {
                                        Display.
    printf("%12s"," ");
    for (i=1;i<=ISCR;i++) printf("%c",scr[i][j]);</pre>
   printf("\n");
```

```
printf(" %10.3f ",ysml);
```

2 int y = 0;4 y += 2; 5 x + = 1;6 }

What is the value of the variable y on line 7?

Preliminary Human Study

- 1 int x = 1;3 while (x<= 5) {
- 7 printf("%d", y);

The amount of training data matters

10% Size of Training Set

100%

The uniqueness of the functions matters

